Multimode Encoder Filter Technology Overview

The encoder, in rotary or linear form, is the most popular motion/position sensor and these filters complement, safeguard, maintain and extend their capabilities and performance.





Terminator multimode encoder signal filter

Mini multimode encoder signal filter

The filters remove all types of electrical noise (common and differential mode, dV/dt transients, ground loop generated etc.) in the encoder signal lines as well as the corrupting effects of mechanical noise and vibration (phantom movement, dither etc.). The filters reconstruct the encoder signals to reflect the correct encoder position and speed signaling. Performance is safeguarded and problems such as:

- · Motion system position drift,
- Home reference loss,
- · False triggering of the receiving inputs, and
- Receiving input saturation, latch-up or failure

are eliminated.

Their design is characterized by typical industrial application considerations: low ownership costs, standard interfacing, fool-proof installation, transparent operation, results-oriented and all-inclusive design. The filters feature the following operational characteristics:

- They are wired in-line between the encoder and the processing equipment. This minimizes and simplifies wiring, usually one of the most significant costs in an installation,
- They interface in a standard way with the encoder outputs and the processing equipment inputs. This enables installation by a non-specialist as well as widening equipment choice,
- They have no special installation requirements, have small physical dimensions and are transparent in operation, and
- They are readily recyclable and made with lead-free materials for minimal impact to the environment.

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Our multimode filters are offered in two standard lines: the fully featured **Terminator** line and the low cost **Mini** line. Both are all-in-one, comprehensive, value-for-money products, each device addressing all and any combination of known encoder application issues. They process digital quadrature encoder signals with the following features and characteristics:

Multimode Frequency Averaging Filter L	ine Features Overviev	v
Feature	Terminator Line	Mini Line
Galvanically isolated input and output stages to interrupt	5 V/ns minimum	0.1 V/ns
unavoidable system ground loops eliminating related noise	dV/dt galvanic	minimum dV/dt
as well as protecting the input stage of the driven controller	barrier immunity.	galvanic barrier
from high voltage transients		immunity.
Four selectable modes of digital processing:	Yes	Yes
1. <u>Unfiltered</u> : the outputs are buffered replicas of the inputs,		
2. <u>Filtered</u> : the encoder inputs are processed for electronic		
noise only,		
3. <u>Recovered x1</u> : the encoder inputs are processed for		
electronic noise and analyzed for mechanical position to recover corrupted motion sequences. The outputs are in		
quadrature format and the mark (or index) channel is		
processed for electrical noise.		
4. <u>Recovered x4</u> : Same as the Recovered x1 mode, but		
with output resolution quadrupling. The output signals		
are a clock/direction or an up/down pair at four times the		
input frequency instead of the quadrature format.		
Test mode . Depending on the chosen mode and sampling	Output is 1/64 the	Output frequency
frequency, the filter outputs simulate the function of a 1024	chosen sampling	is fixed.
ppr encoder.	frequency.	
Direction reversal. One of the encoder channels can be	Yes	Yes
complemented to effect a direction reversal, thus saving the		
rewiring/reconnection of the encoder signals.		
Supply, signal and worn/faulty encoder indication. Five	Yes	Yes
LEDs indicate the status of the power supply, the three		
encoder channels and the presence of out-of-sequence		
signalling, typically caused by a worn or faulty encoder.		
DIP switch selectable options . All operational parameters	Yes	Yes
are set/reset via DIP switches.	EE24 model enhy	Vaa
Independent, galvanically-isolated fault output. The out-	EF24 model only	Yes
of-sequence condition activates this uncommitted		
optotransistor output interfacing to external systems. Selectable sampling frequency. The encoder signals are	Yes	Yes
DSP processed at selectable frequencies to interface to	165	163
slower equipment or tune out problem noise sources in		
particularly difficult applications.		
Types of EIA(RS)422 input termination.	Standard DC, AC	Standard DC and
· · · · · · · · · · · · · · · · · · ·	and none	none
Internal dual voltage 115/230 VAC twin supply. Powers	Yes	No. Power must
the two internally isolated input and output filter sections		be supplied to
and can power the monitored encoder with regulated 5 VDC		each of the input
or unregulated 10/15 VDC.		and output filter
		sections.
Enclosure	Cast aluminium,	Plastic, DIN rail
	high noise immunity,	mountable, IP40
	IP65	
Available speed grades.	High, Standard and	Basic only
	Low	

The Terminator Line



The Terminator multimode filters are all-in-one, valuefor-money products addressing high speed, high noise immunity and high environmental protection requirements.

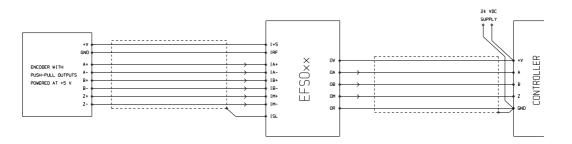
They feature an internal dual voltage 115/230 VAC twin supply which powers the two internally isolated input and output filter sections and can also power the monitored encoder with regulated 5 VDC or unregulated 10/15 VDC.

The line is offered in a range of options which also allow them to be used as interfaces between different encoder and PLC/drive input card signal types. These are:

	Terminator Multimode Encoder Filter Model Selection Table					
Model	Single ended input types	Differential input types	Universal 5 V output types	5-30 V output types	Available speed grades	
EF24	All 10-28 V types	10-28 V		All types	Low	
EFDO		EIA422	EIA422, all single 5V		High, Standard	
EFSO	All 5 V, 5-30 V NPN and push-pull only	EIA422		PNP, push-pull	Low	
EFU5	All 5 V, 5-30 V NPN and push-pull only	EIA422	EIA422, all single 5V		High, Standard	

The maximum quadrature input frequency which can be processed by the filters depends on the filter speed grade and function mode as follows:

Maximum Quadrature Input Frequency Capability per Filtering Mode				
Speed Version	Unfiltered	Filtered	Recovered x1	Recovered x4
Low	300 kHz	250 kHz	200 kHz	62.5 kHz
Standard	10 MHz	1.5 MHz	1.2 MHz	375 kHz
High	10 MHz	3.0 MHz	2.4 MHz	1.5 MHz



Typical application of an EFSOxx filter powering a physically remote encoder (connected via long cables), processing its differential output signals and interfacing them to a 24 V single input controller.

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The Mini Line



The Mini multimode filters are all-in-one, value-for-money products addressing less demanding and low cost needs.

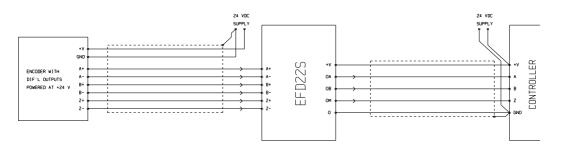
They feature an IP40 DIN rail mountable enclosure and have no internal supply to power the filter input and output sections. The input and output stages are typically powered by the monitored encoder and receiving controller/PLC supplies respectively.

The line is offered in a range of options which also allow them to be used as interfaces between different encoder and PLC/drive input card signal types. These are:

Mini Multimode Encoder Filter Model Selection Table					
Model	Single ended input types	Differential input types	Single ended output types	Differential output types	Power supply
EFD44		EIA422		EIA422	5 VDC (input) and 5 VDC (output)
EFD42S		EIA422	10-28 V PNP and push-pull only		5 VDC (input) and 10-28 VDC (output)
EFD42D		EIA422	All 10-28 V	10-28 V	5 VDC (input) and 10-28 VDC (output)
EFD24	All 10-28 V	All 10-28 V		EIA422	10-28 VDC (input) and 5 VDC (output)
EFD22S	All 10-28 V	All 10-28 V	10-28 V PNP and push-pull only		10-28 VDC (input) and 10-28 VDC (output)
EFD22D	All 10-28 V	All 10-28 V	All 10-28 V	10-28 V	10-28 VDC (input) and 10-28 VDC (output)

The maximum quadrature input frequency which can be processed by the filters depends on the selected function mode as follows:

Maximum Quadrature Input Frequency Capability per Filtering Mode				
Speed Grade	Unfiltered	Filtered	Recovered x1	Recovered x4
Basic	300 kHz	125 kHz	100 kHz	31.3 kHz



Typical application of an EFD22S filter powering a physically remote encoder (connected via long cables), processing its differential output signals and interfacing them to a 24 V single input controller.

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Other products of interest



The specialty multimode frequency averaging filters, after cleaning-up and ensuring the electrical and low-level integrity of the encoder signals, process these signals to reproduce them at average input frequency.

The technology and its applications are described in document *Multimode Frequency Averaging Filters* (also available from our site http://www.cognitoquam.gr).

Our encoder filter technology is also offered in custom versions for OEMs (Original Equipment Manufacturers).



Multimode Encoder Signal Filter Ordering Information					
M	odel			Description	
Clock/direction	Up/down	Filter line Speed Input → Out		Input → Output	
x4 output	x4 output		grade		
EF2402-ALU-L	EF2402U-ALU-L	Terminator	Low	Universal 10-28 V → Universal 5-30	
				V	
EFDO02-ALU-H	EFDO02U-ALU-H	Terminator	High	EIA(RS)422 → Universal 5 V	
EFDO02-ALU-S	EFDO02U-ALU-S	Terminator	Standard	EIA(RS)422 → Universal 5 V	
EFSO02-ALU-L	EFSO02U-ALU-L	Terminator	Low	Universal 5 V \rightarrow PNP/push-pull type	
				5-30 VDC single ended	
EFU502-ALU-H	EFU502U-ALU-H	Terminator	High	Universal 5 V \rightarrow Universal 5 V	
EFU502-ALU-S	EFU502U-ALU-S	Terminator	Standard	Universal 5 V \rightarrow Universal 5 V	
EFD44-DIN-B	EFD44U-DIN-B	Mini	Basic	EIA422 → EIA422	
EFD42S-DIN-B	EFD42SU-DIN-B	Mini	Basic	EIA422 → 10-28 V PNP/push-pull	
				single ended	
EFD42D-DIN-B	EFD42DU-DIN-B	Mini	Basic	EIA422 → Universal 10-28 V	
EFD24-DIN-B	EFD24U-DIN-B	Mini	Basic	Universal 10-28 V → EIA422	
EFD22S-DIN-B	EFD22SU-DIN-B	Mini	Basic	Universal 10-28 V \rightarrow 10-28 V	
				PNP/push-pull single ended	
EFD22D-DIN-B	EFD22DU-DIN-B	Mini	Basic	Universal 10-28 V → Universal 10-	
				28 V	

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Cognito Quam Profile

Cognito Quam Electrotechnologies Ltd. (established in 1990) is a privately held engineering and commercial company specializing in industrial electronics and their application. The company expertise covers all aspects of applications for the factory environment namely measurement (transducers and sensors), data processing and communication, control and actuation, automation and robotics and power and energy electronics.

Cognito Quam has contributed and been involved in the design and development of the following technologies, machinery and devices:

- Power factor controllers,
- Motor voltage and frequency inverters and converters,
- Thermal load control and management,
- Robotic interfaces and protocol converters,
- Adaptive panel controllers,
- Robotics controllers,
- Variable speed drives,
- Olive oil processing rejects control equipment (FAIR contract),
- Low Voltage and EMC CE marking compliance devices and equipment for production lines,
- Portable dioxine-furan instrumentation (SMT contract),
- Three-phase programmable soft-starters,
- Hard real time job scheduling systems,
- Hard real time industrial distributed data systems (Brite-EuRam subcontract),
- Calibration rig and supplies for power meters,
- Electrical utility Hall effect energy and power meters,
- Industrial data networks,
- Battery chargers and UPS inverters,
- Solar power air conditioning telemetry and control systems (Thermie subcontract)
- Small switching power supplies,
- Multi-port communication PC cards,
- Ship oily water separators, and
- Modem controllers.

Cognito Quam also offers its research and development services in integrating its products in larger industrial systems products as well as in the design of new and challenging devices and equipment. As such the company cooperates closely and supports its customers in their efforts for a better product.